

# Towards an open source MDE tool infrastructure for the Internet of Things

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EXE 2017

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co-located with **MODELS 2017**

# The Internet of Things (IoT)

Technology for collection, aggregation, and analysis of data from range of devices to optimize operation of a system in different domains, including buildings, traffic, health care, energy, business, industry

*And, please, don't forget to buy milk **again!***



*You should walk these short distances in the future.*



EXE'17

*Can you turn me around?  
I look fuller from the other side.*



# IoT: Core Characteristics

timed  
reactive  
concurrent

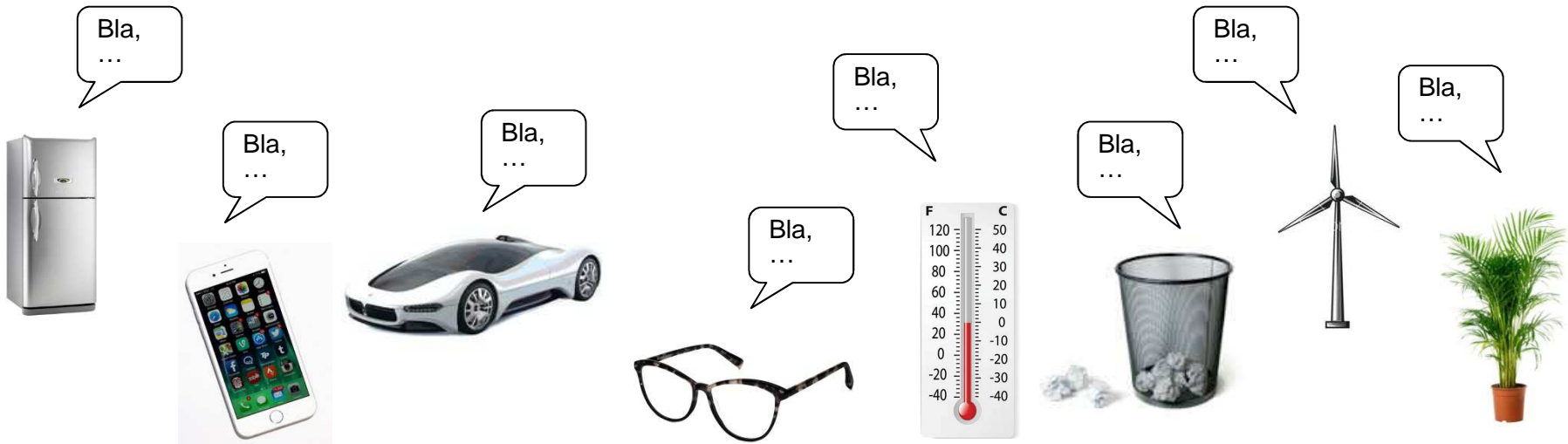
distributed

open  
heterogenous

self-optimizing  
context-aware  
autonomous  
adaptive

large scale

available  
reliable



J. Dingel

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# MDE

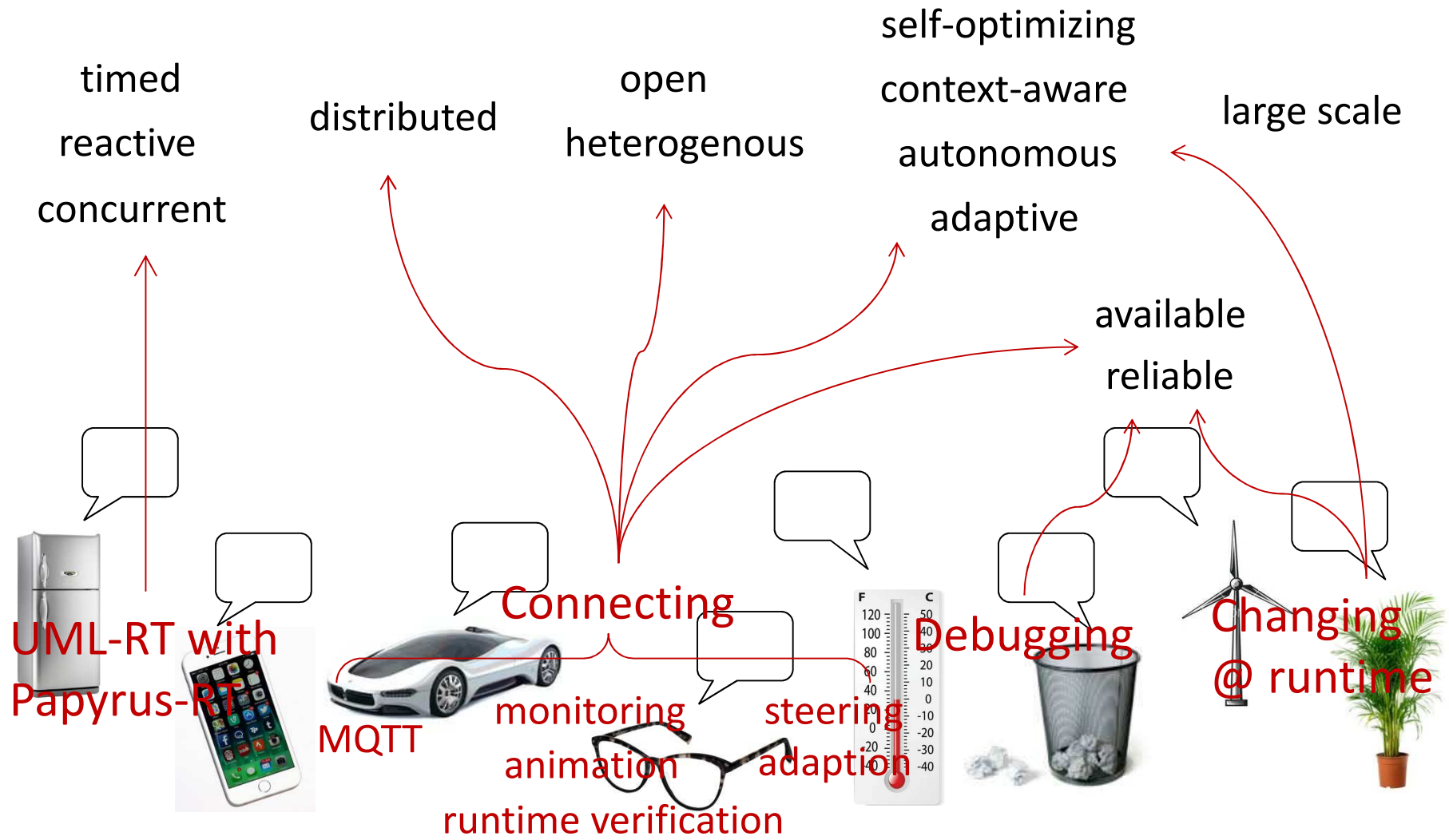
- MDE = notations, techniques, tools to leverage abstraction and automation for system development
- Examples for abstraction and automation
  - Virtual memory [Denning 1970]
  - Internet Protocol [Cerf 2017]
- Examples for MDE
  - Robotics software [SPARC 2016]
  - Industrial DSLs (e.g., at Ericsson)
  - Game development (e.g., in Unity)

[Denning 1970] P. Denning. Virtual Memory. ACM Computing Surveys 2(3):153-189. 1970

[Cerf 2017] V.G. Cerf. In Praise of Underspecification? CACM 60(8):7. Aug 2017

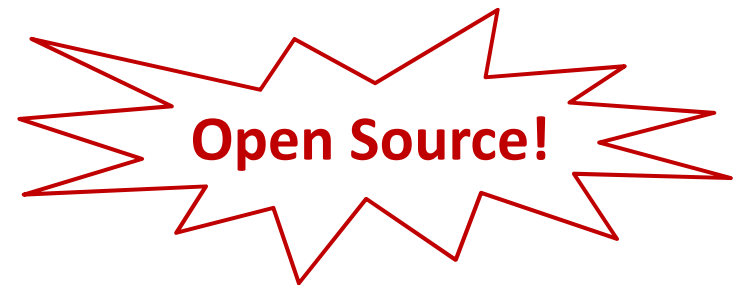
[SPARC 2016] SPARC. Robotics 2020 Multi-Annual Roadmap: For Robotics in Europe, Horizon 2020 Call ICT-2017 (ICT-25, ICT-27 & ICT-28). Dec 2016.

# Overview of Talk



# Goal of Talk

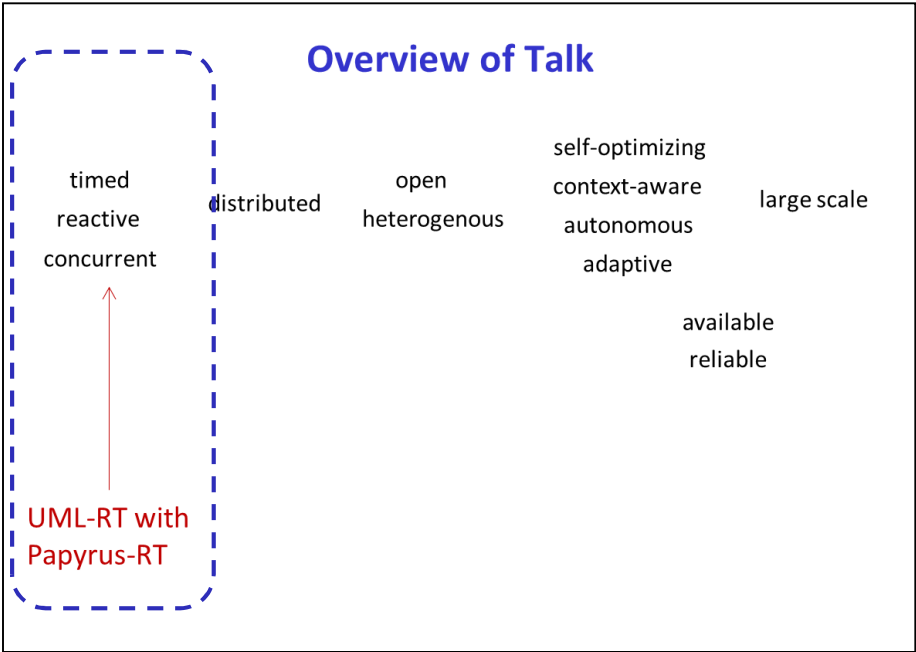
- **Inform**
  - MDE with UML-RT and Papyrus-RT and extensions
- **Inspire**
  - Use, extend, participate





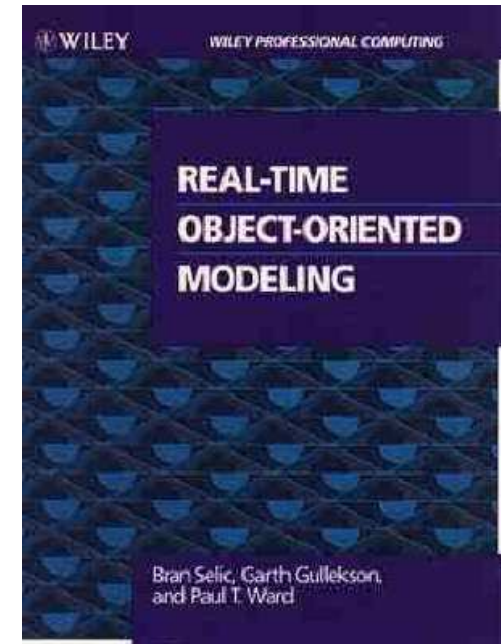
Background

MDE with UML-RT  
and Papyrus-RT



# UML-RT: History

- Real-time OO Modeling (ROOM)
  - ObjecTime, early 1990 ties
- Major influence on UML 2
  - E.g., StructuredClassifier
- “RT subset of UML”
- Tools
  - ObjecTime Developer
  - IBM Rational RoseRT
  - IBM RSA-RTE
  - Protos ETrice
  - Eclipse Papyrus-RT



[Selic, Gullekson, Ward.  
*Real-Time Object-Oriented  
Modelling*. Wiley. 1994]

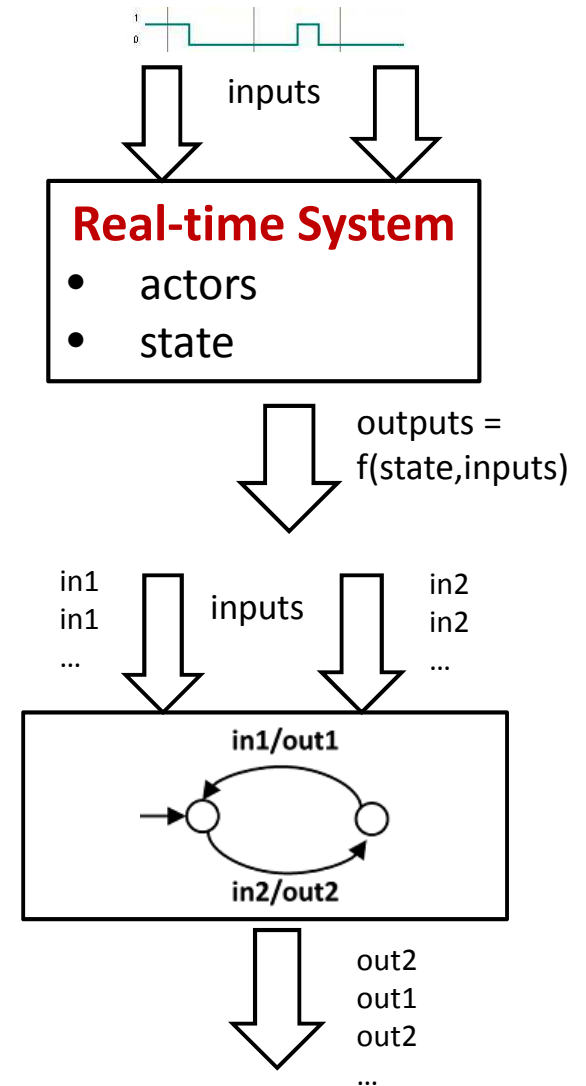


# UML-RT: Characteristics

- **Domain-specific**
  - Embedded systems with soft real-time constraints
- **Graphical**, but textual syntax exists
- **Small, cohesive set of concepts**
- **Strong encapsulation**
  - Actors (active objects)
  - Explicit, typed interfaces
  - Message-based communication
- **Event-driven execution**
  - State machines
- **Lots of analysis opportunities**

*“UML-RT has features that appeal to the formalist”*  
[Whittaker et al 2000]

[Whittaker et al 2000] P. Whittaker, M. Goldsmith, K. Macolini, T. Teitelbaum. “Model checking UML-RT protocols”. Workshop on Formal Design Techniques for Real-Time UML. York, UK. Nov. 2000.



# UML-RT: Core Concepts (1)

## ■ Types

- Capsules (active classes)
  - Capsule instances (parts)
- Passive classes (data classes)
  - Objects
- Protocols
- Enumerations

## ■ Structure

- Attributes
- Ports
- Connectors

## ■ Behaviour

- Messages (events)
- State machines

## ■ Grouping

- Package

## ■ Relationship

- Generalization
- Associations

# UML-RT: Core Concepts (2)

## ■ Model

- Collection of **capsule** definitions
- 'Top' capsule containing collection of **parts** (capsule instances)

## ■ Capsules

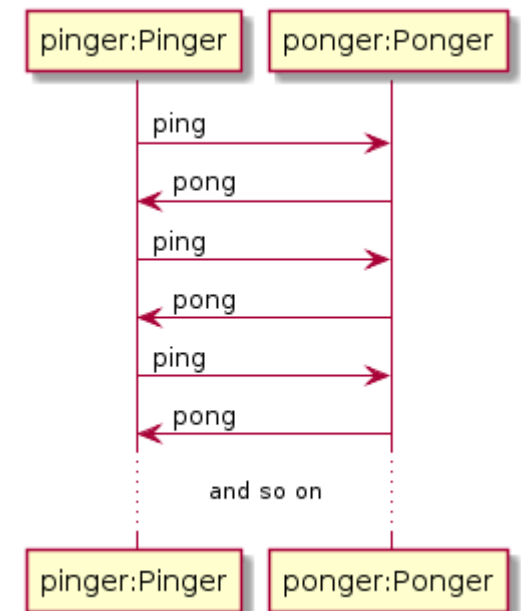
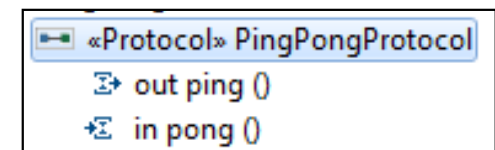
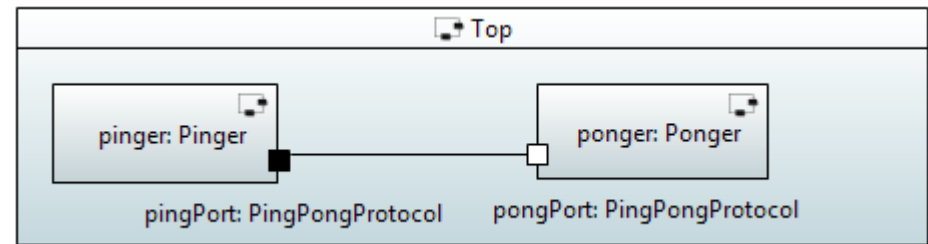
- May contain
  - **Attributes, ports, or other parts**
- Behaviour defined by **state machine**

## ■ Ports

- Typed over **protocol** defining **input and output messages**

## ■ State machine

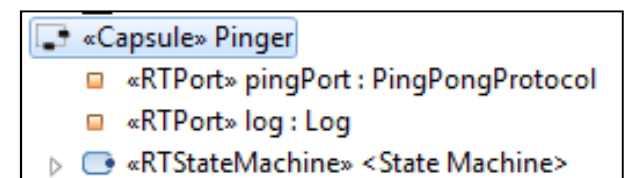
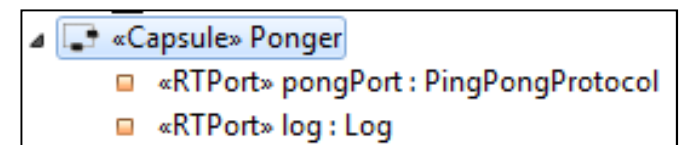
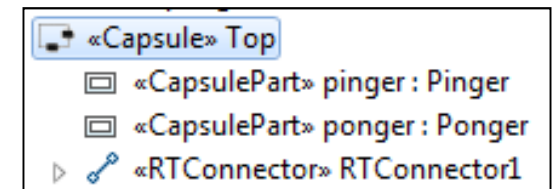
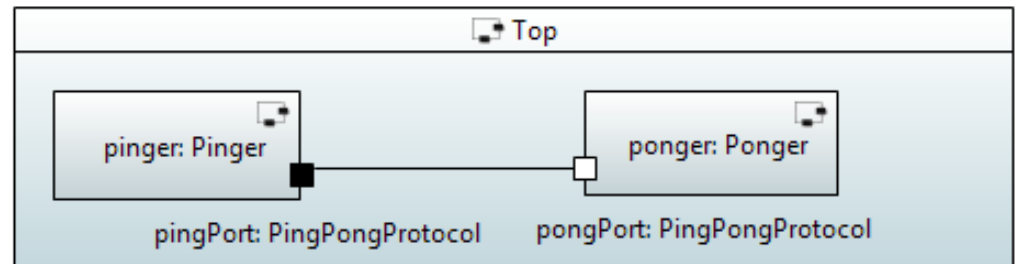
- **Transition** triggered by incoming messages
- **Action code** can contain send statements that send messages over certain ports



# Capsules (1)

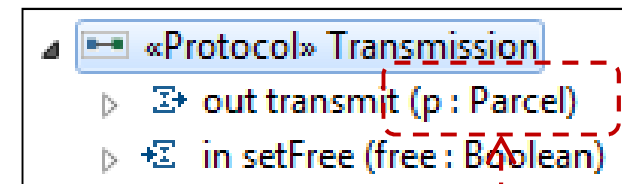
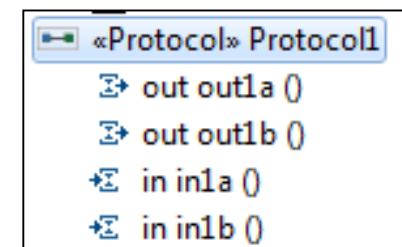
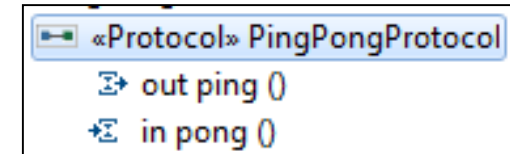
- Kind of **active class**
  - Attributes, operations
  - Own, independent flow of control (logical thread)
- May also contain
  - **Ports** over which messages can be sent, received
  - **Parts** (instances of other capsules) and **connectors**
- Creation, use of instances **tightly controlled**
  - Created by runtime system (RTS)
  - Cannot be passed around
  - Stored in attribute of another capsule (**part**)
  - Information flow only via messages sent to ports

⇒ **better concurrency control and encapsulation**
- Behaviour defined by **state machine**



# Protocols

- Provide types for ports
- Define
  - Input messages
    - Services **provided** by capsule owning port
  - Output messages
    - Services **required** by capsule owning port
  - Input/output messages
- Messages can carry **data**



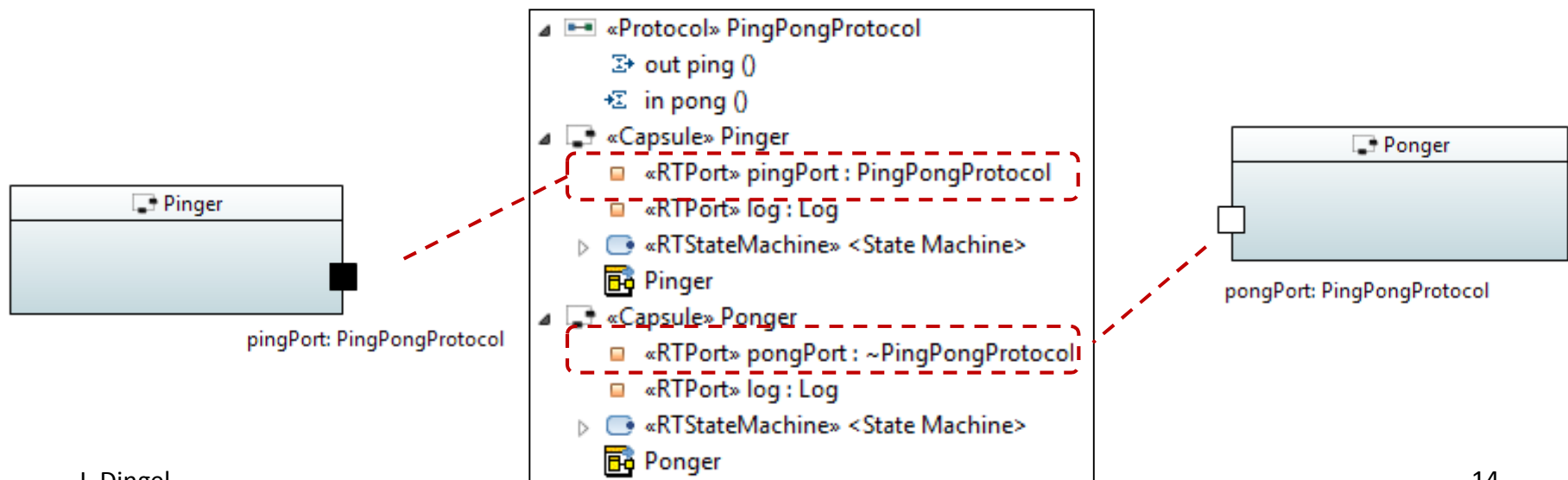
# Ports

- “Boundary objects” owned by capsule
- Typed over a protocol P
- Have ‘**send**’ operation

```
portName.msg(arg1, ..., argn).send()
```

- E.g., in **Pinger**

```
pingPort.ping().send()
```



# Ports: External, Internal, Relay

## External behaviour

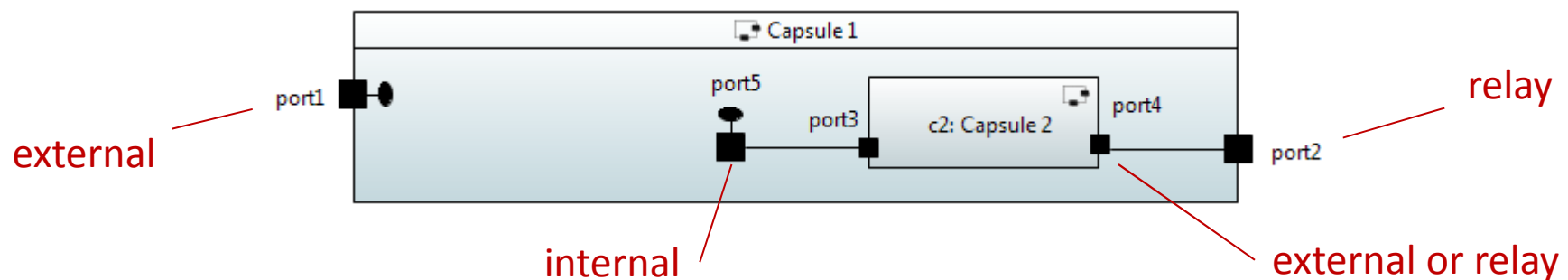
- Provides (part of) **externally visible functionality** (isService=true)
- Incoming messages passed on to state machine (isBehaviour=true)
- Must be connected (isWired=true)

## Internal behaviour

- As above, but **not externally visible** (isService=false)
- Connect state machine with a capsule part

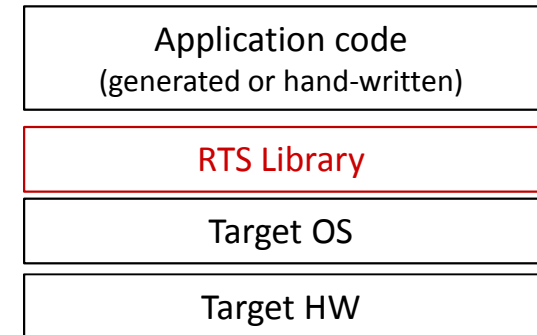
## Relay

- Pass external messages to and from capsule parts



# Ports: System

- Connects capsule to **Runtime System (RTS)** library via corresponding system protocol
- Provides access to RTS services such as

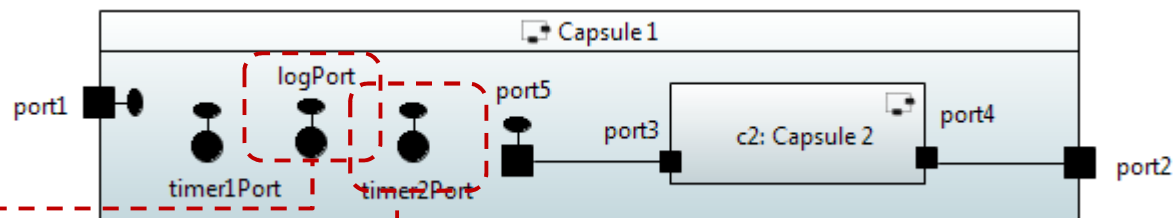


- **Timing:** setting timers, time out message

- `timer2Port.informIn(UMLRTTimespec(10, 0));`  
// set timer that will expire in 10 secs and 0 nanosecs
- When timer expires, 'timeout' message will be sent over `timer2Port`

- **Log:** sending text to console

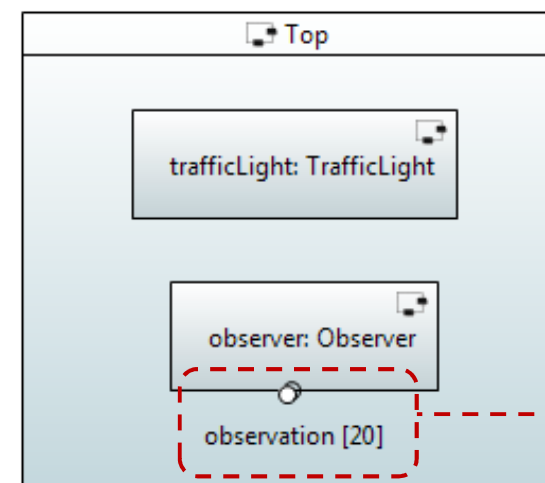
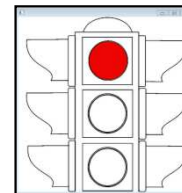
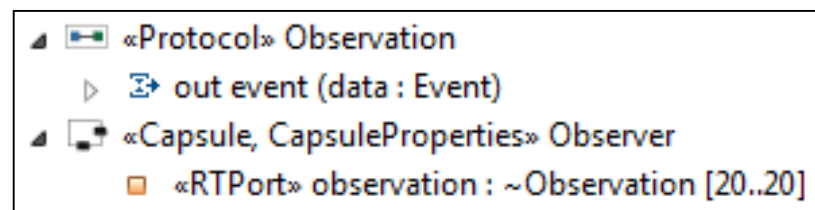
- `logPort.log("Ready to self-destruct")`



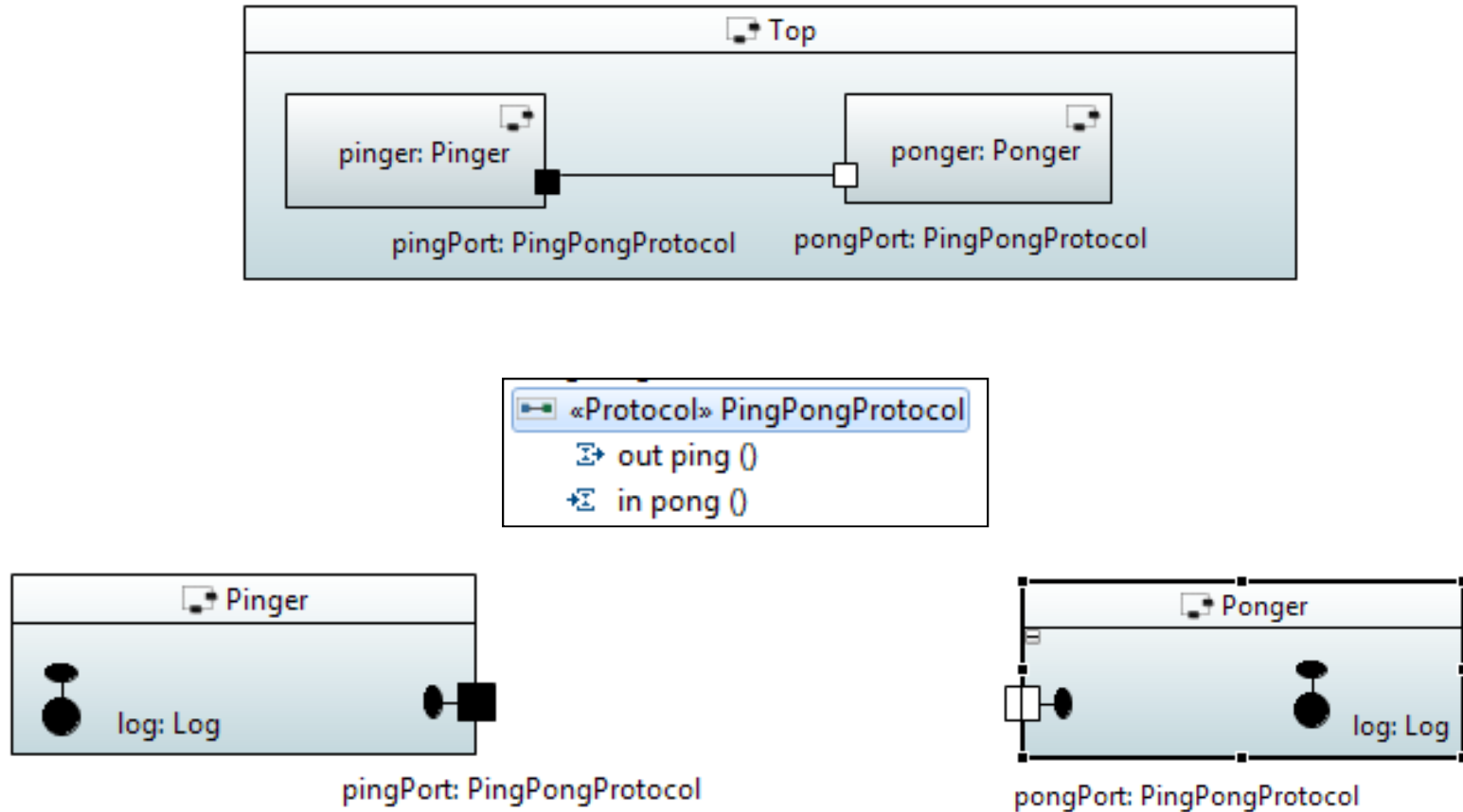


# Ports: SPP and SAP

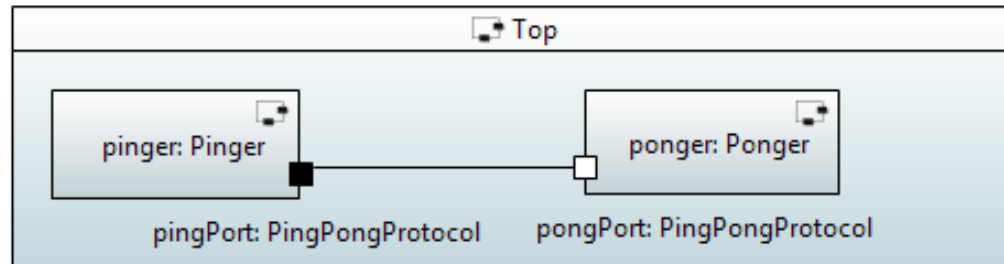
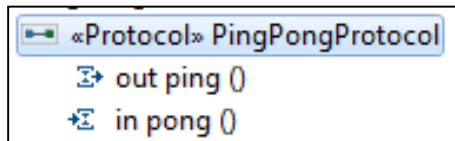
- So far, only **wired ports**
  - Connected automatically when instances are created
- **Unwired ports**
  - Original intent: 'layered' design
  - Connected at run-time
    - Port on provider: **Service Provision Point (SPP)**
    - Port on user: **Service Access Point (SAP)**
    - Register with RTS using unique service name (manually or automatic)



# Example: Ping Pong



# Example: Ping Pong

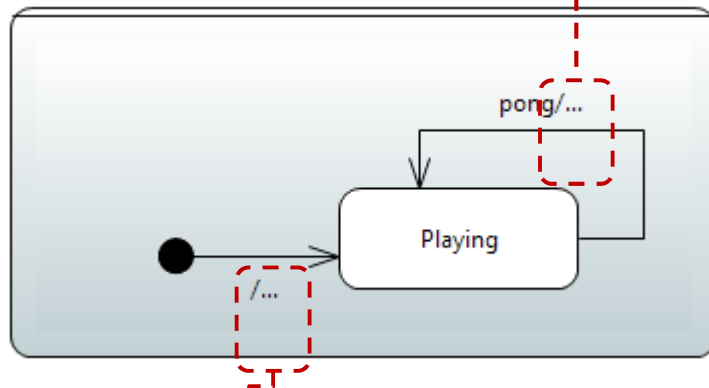


```

$ ./TopMain.exe
Controller "DefaultCon
Pinger: ready
Pinger: sending ping
Ponger: ready
Ponger: received ping
Ponger: sending pong
Pinger: received pong
Pinger: sending ping
Ponger: received ping
Ponger: sending pong
Pinger: received pong
Pinger: sending ping
Ponger: received ping
Ponger: sending pong
Pinger: received pong
Pinger: sending ping
Ponger: received ping
Ponger: sending pong
Pinger: received pong
Pinger: sending ping
  
```

```

log.log("Pinger: received pong");
log.log("Pinger: sending ping");
pingPort.ping().send();
  
```

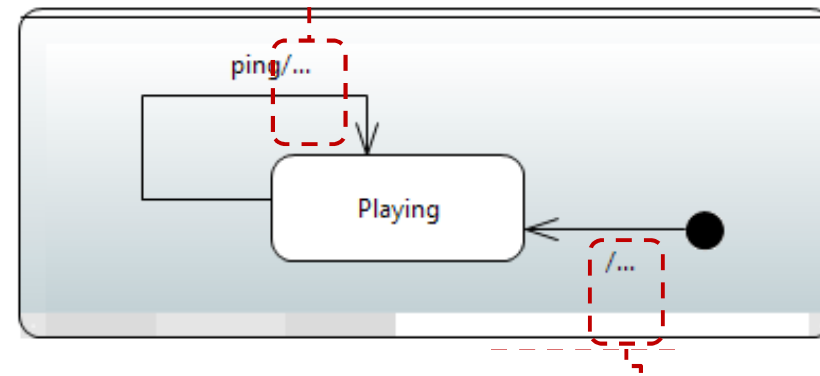


```

log.log("Pinger: ready");
log.log("Pinger: sending ping");
pingPort.ping().send();
  
```

```

log.log("Ponger: received ping");
log.log("Ponger: sending pong");
pongPort.pong().send();
  
```



```

log.log("Ponger: ready");
  
```

# Papyrus-RT: Overview



- **Papyrus for Real-Time** industrial-grade, complete modeling environment for the development of complex, software intensive, real-time, embedded, cyber-physical systems.
- Part of **PolarSys**
  - Eclipse Working Group
  - Open source for embedded systems
- **Building on**
  - Eclipse Modeling Framework (EMF), Xtext, Papyrus
- **History**
  - 2015: V0.7.0
  - March 2017: v0.9
  - Fall 2017: v1.0



[\[https://wiki.eclipse.org/Papyrus-RT\]](https://wiki.eclipse.org/Papyrus-RT)

# Resources: UML-RT and Papyrus-RT

## ■ UML-RT

- Papers:
  - B. Selic. Using UML for Modeling Complex Real-time Systems. Workshop on Languages, Compilers, and Tools for Embedded Systems (LCTES'98)
  - E. Posse, J. Dingel. An Executable Semantics for UML-RT. SoSyM 15(1):179-217. 2016
- Tutorials:
  - MODELS'17, <http://flux.cs.queensu.ca/mase/papyrus-rt-resources/supporting-material-for-the-models17-tutorial/>
  - EclipseCon'17, <http://flux.cs.queensu.ca/mase/papyrus-rt-resources/supporting-material-for-eclipsecon17-unconference/>

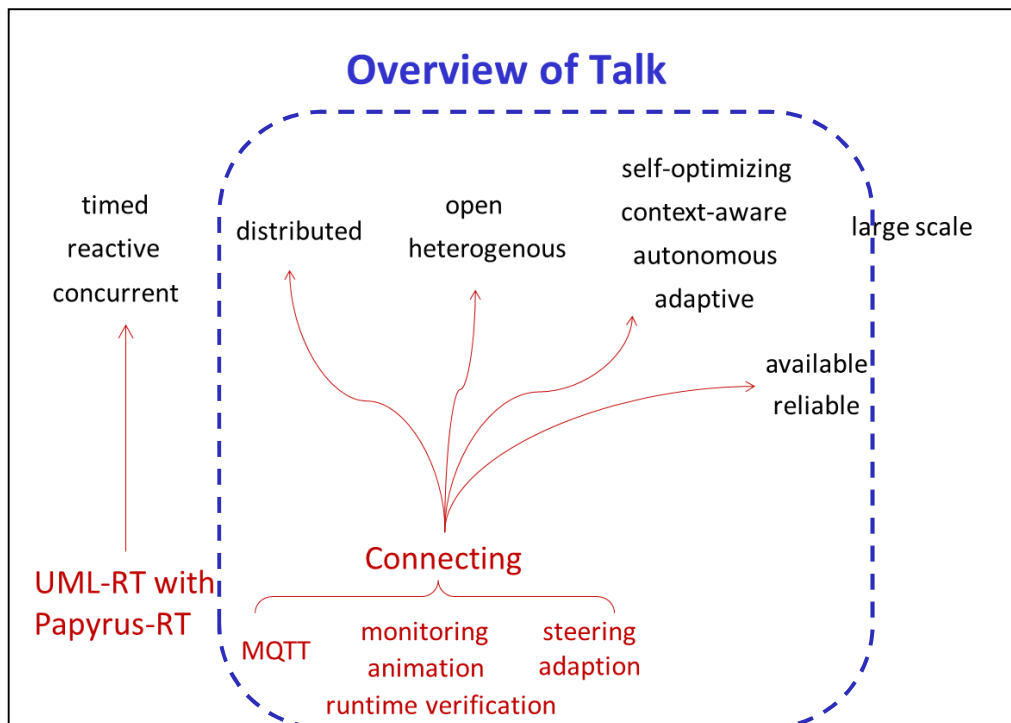
← This  
afternoon!

## ■ Papyrus-RT

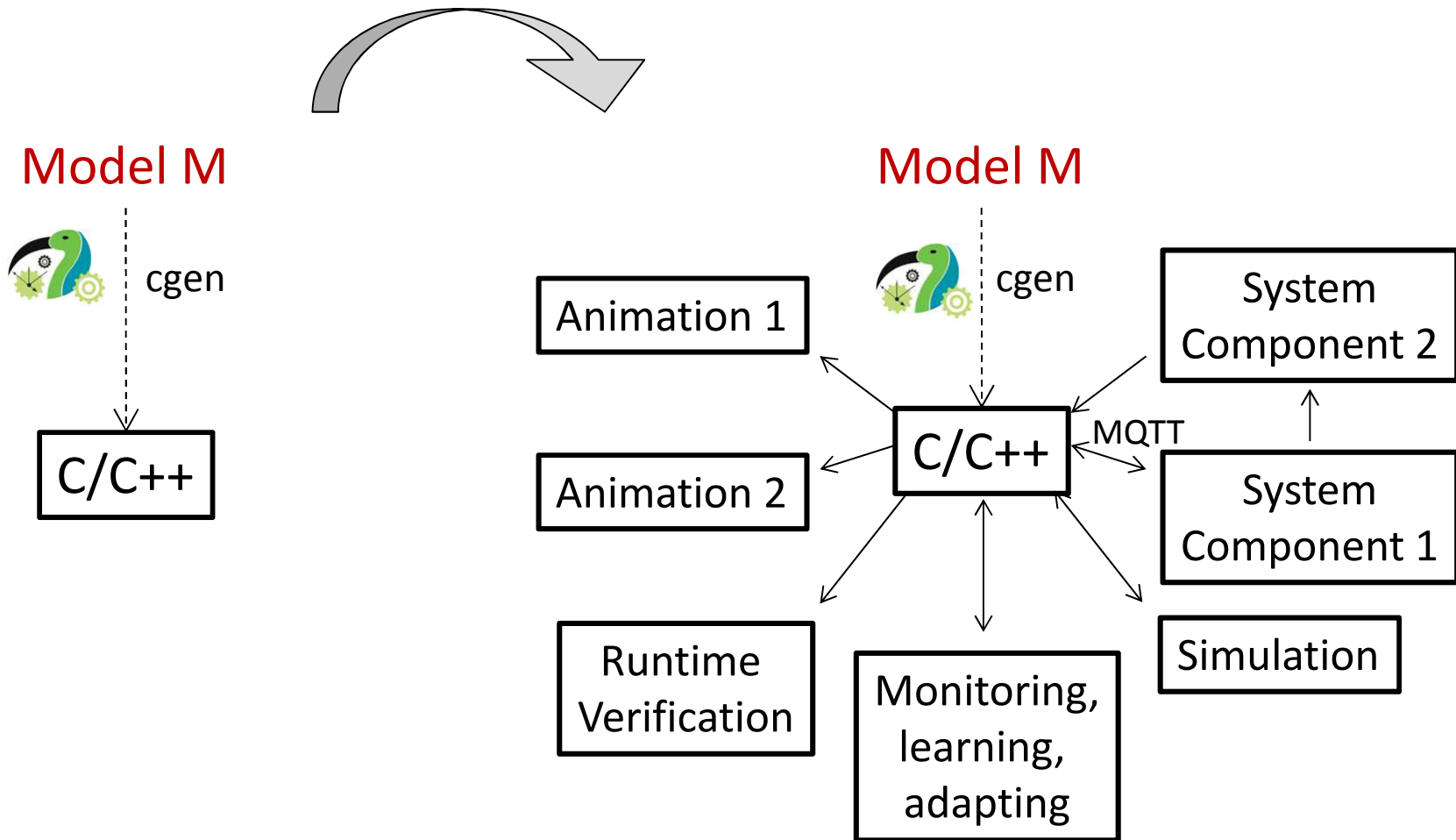
- Distribution: <https://eclipse.org/papyrus-rt>
- Wiki: <https://wiki.eclipse.org/Papyrus-RT>
- Overview: <https://www.youtube.com/watch?v=UqefL7-ZPYo>

# Ongoing Research 1

## Connecting

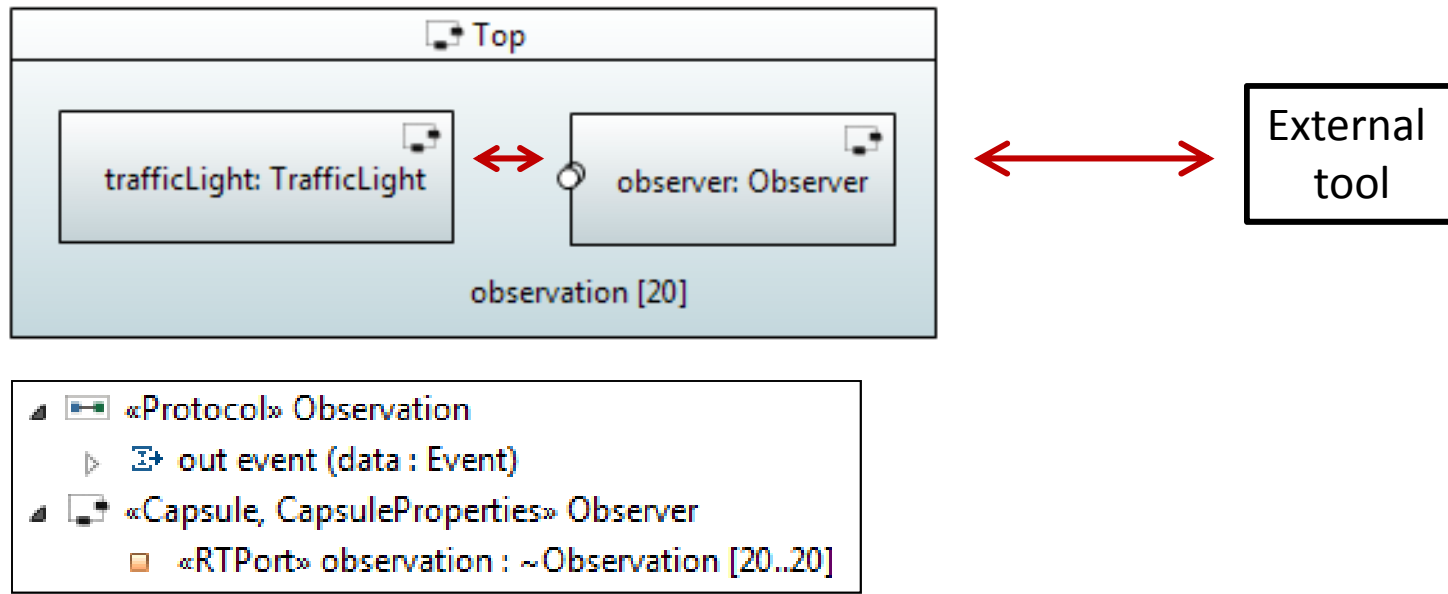


# From Isolated to Connected



# Mechanism 1: Gateway Capsule

- Using SAP/SPP
  - Protocol defines incoming/outgoing messages
  - Automatic registration
- Bi-directional
  - Incoming messages can trigger transitions

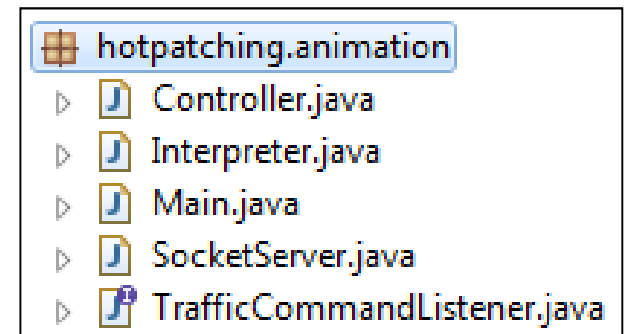
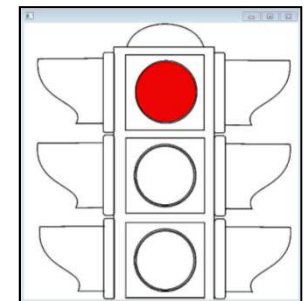
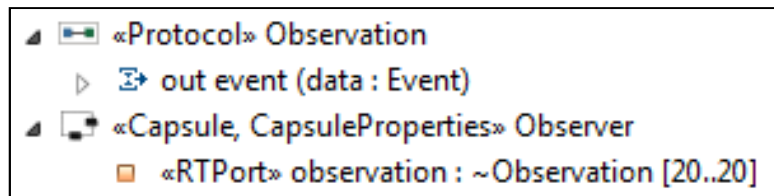
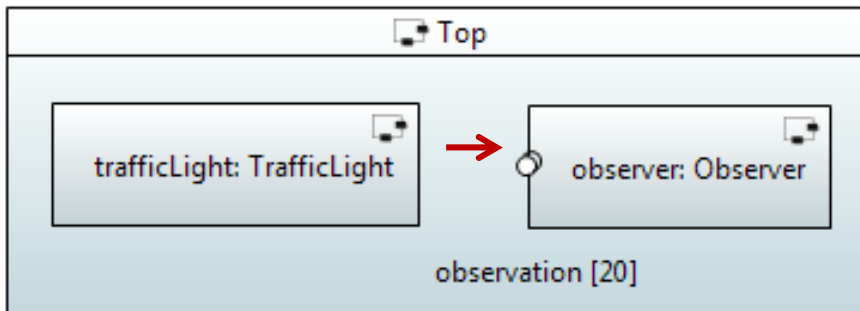
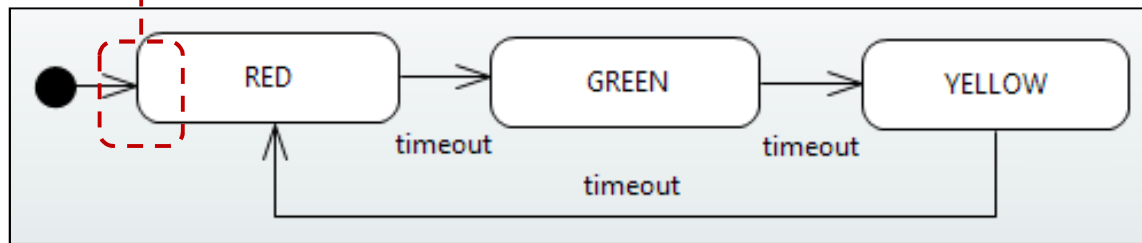






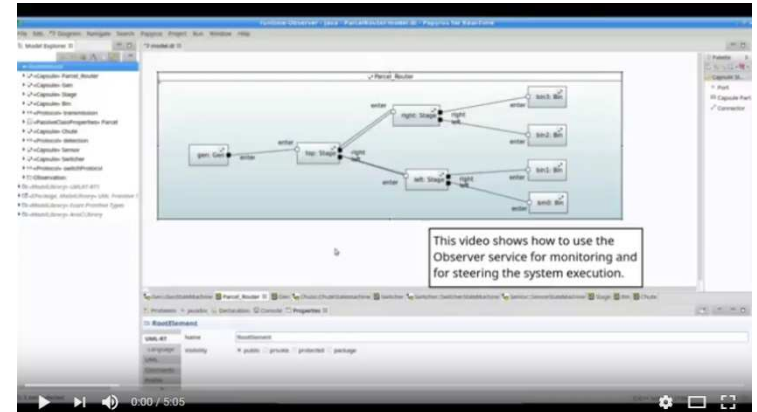
# Gateway Capsule: Example


```
Event e1;  
e1.setParam("id", "top");  
e1.setParam("color", "#ef0404");  
e1.setParam("cmd", "set_color");  
observation.event(e1).send();  
  
timer.informIn(UMLRRTimespec(5,0));  
log.show("Switched to red\n");
```



# Gateway Capsule: Examples

- **Monitoring and steering**
  - Parcel routing system
  - <https://www.youtube.com/watch?v=EbMIgEX9O58>



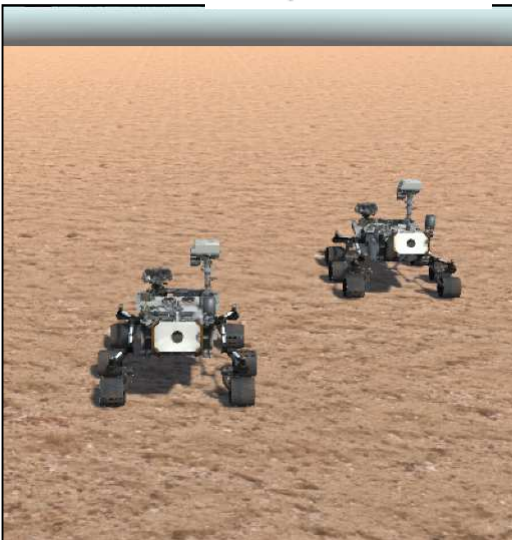


```

Object Wally : Rover {
  config {
    posx = 0
    posy = 1
    posz = 0
    size = 1
    brake = 20
    power = 100
    network = true
  }
}

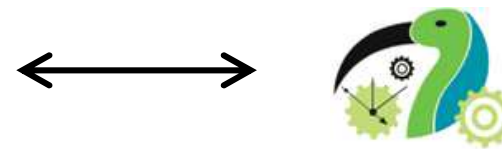
Object Eva : Rover {
  config {
    posx = 5
    posy = 1
    posz = 5
    size = 1
    brake = 20
    power = 100
    network = true
  }
}

Env simulation {
  Instance plane : land
  Instance eva : Eva
  Instance ourRover: Wally
  Channel myChannel direction inout type TCP (port : 8888) assign ourRover
}
        
```



EXE'17

- **Animation and simulation using Unity**



[Diagrams courtesy  
Michal Pasternak]

# Mechanism 2: MQTT

## Message Queue Telemetry Transport (MQTT)

- Publish/subscribe protocol
- Light-weight, low resource requirements
- Easy to use:  
(dis-)connect, (un-)subscribe, publish
- Standardized

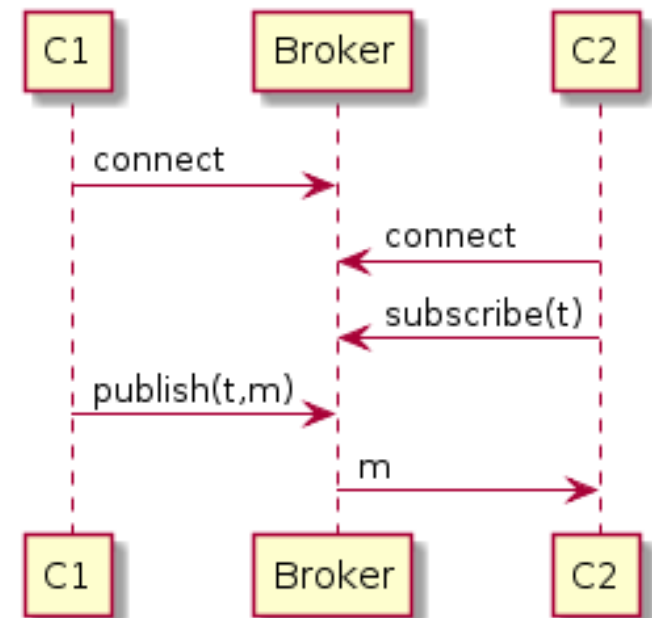
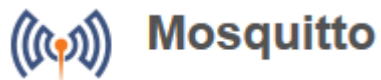
## Implementations

- E.g., Eclipse Paho



## Brokers

- E.g., Eclipse Mosquitto



Topic	Subscribers
"Temperature/bedroom"	Component 2
...	...

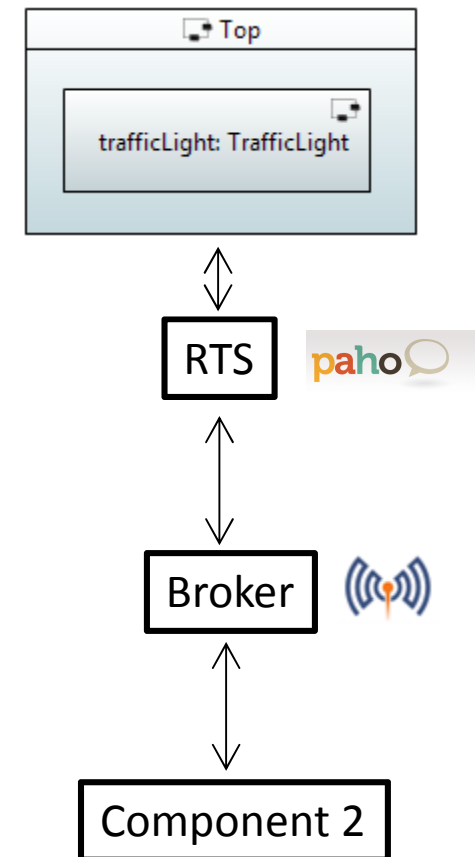
# MQTT Support in Papyrus-RT

## ■ In model

- Subscribe(t) in capsule C
  - register unwired port of C as SAP under name t
- Publish(t,m) in capsule C
  - send m to port of C associated with t

## ■ RTS

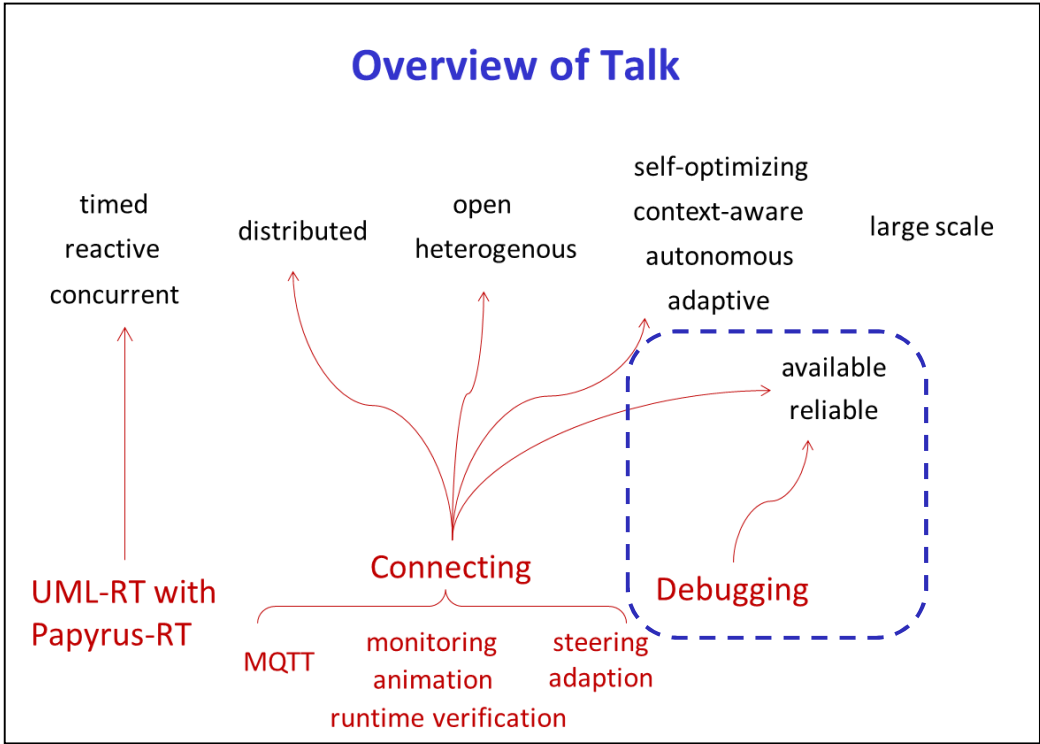
- Maintains connection to broker(s) and topic/broker table
- Sends published messages to corresponding broker(s)
- Periodically checks brokers for incoming messages
- Sends incoming message m to port associated with m





Ongoing Research 2

Debugging



# Model Debugging: Two Approaches

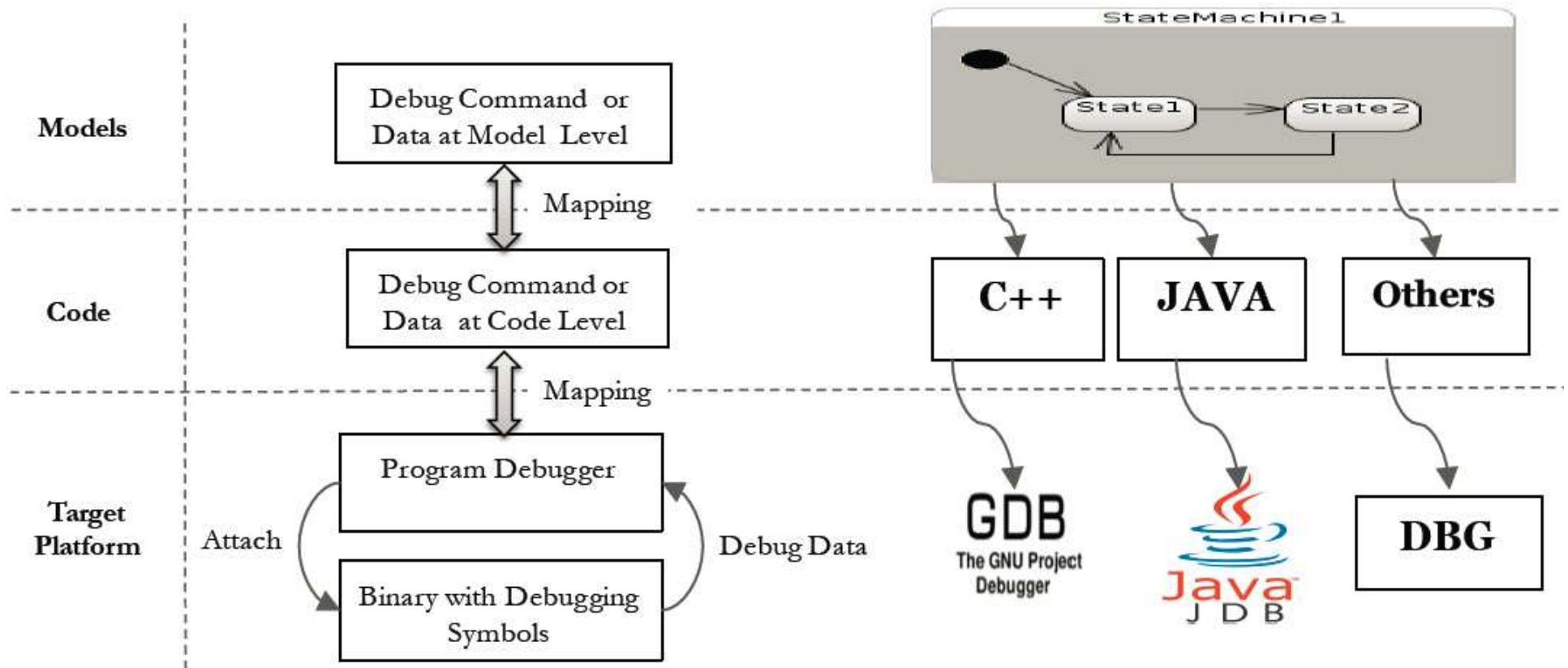
## 1. Interpretation

- Pros
  - Easier to integrate into MDE environment
- Cons
  - Two semantics: Interpreter vs code generator
  - Two platforms: Modeling platform vs target platform

## 2. Executing generated code on target platform

- Pros
  - One semantics, one platform
- Cons
  - How to implement?

# Existing Approaches



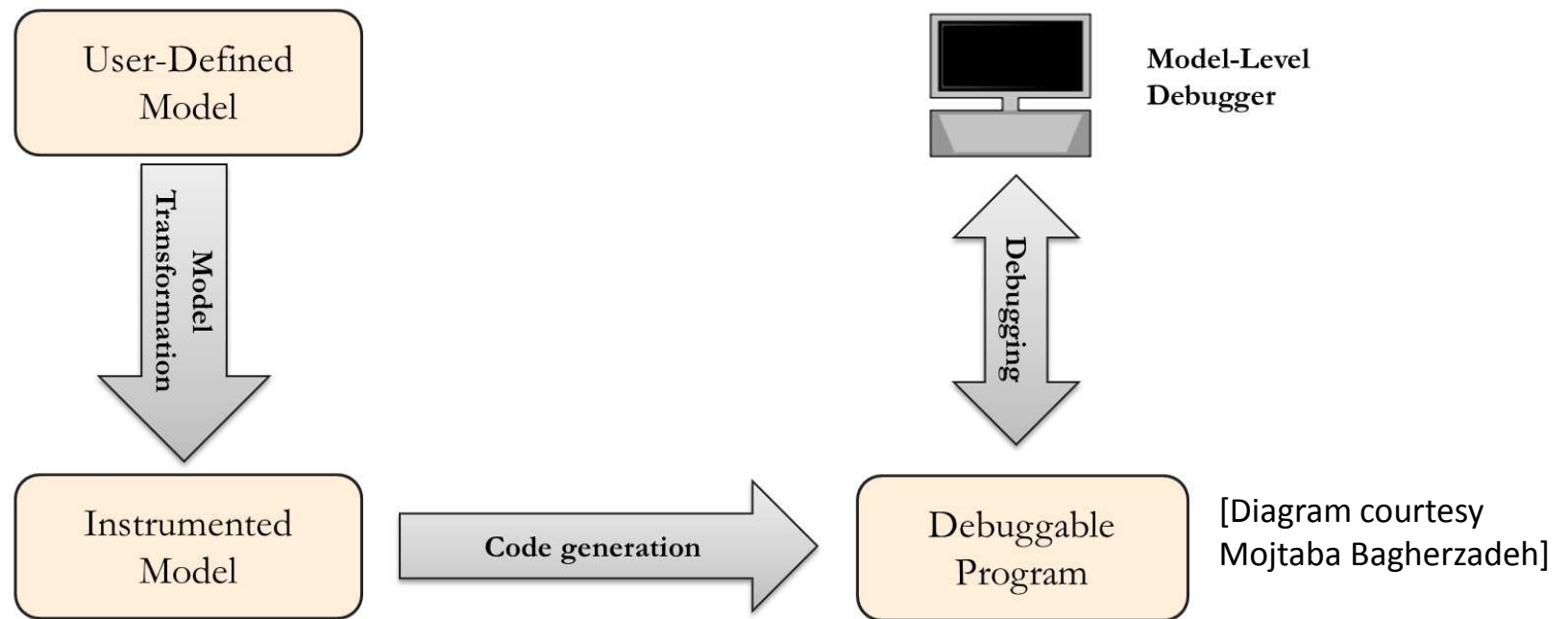
[Diagram courtesy Mojtaba Bagherzadeh]

## Consequences?

# Our Approach

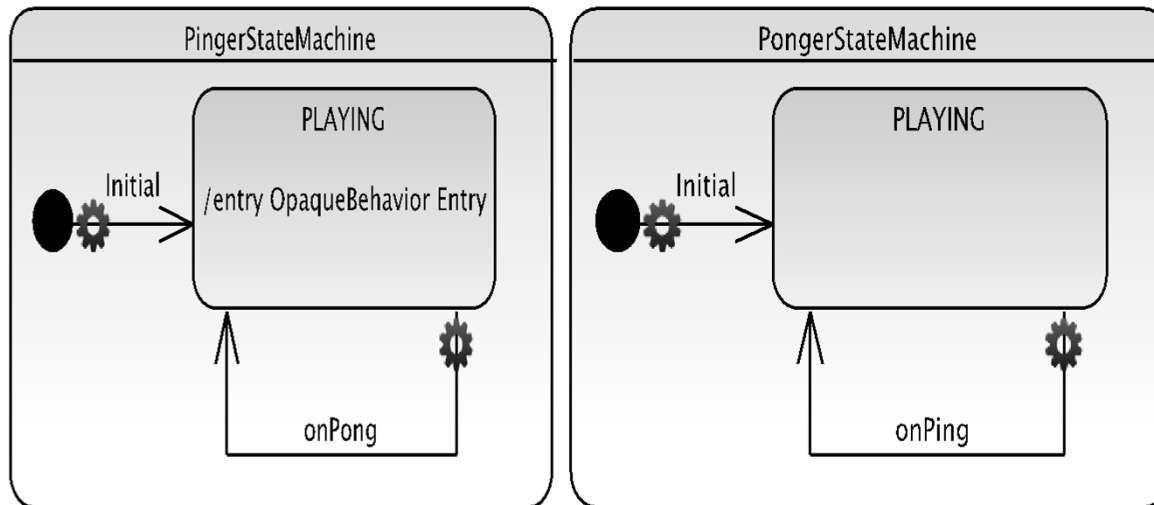
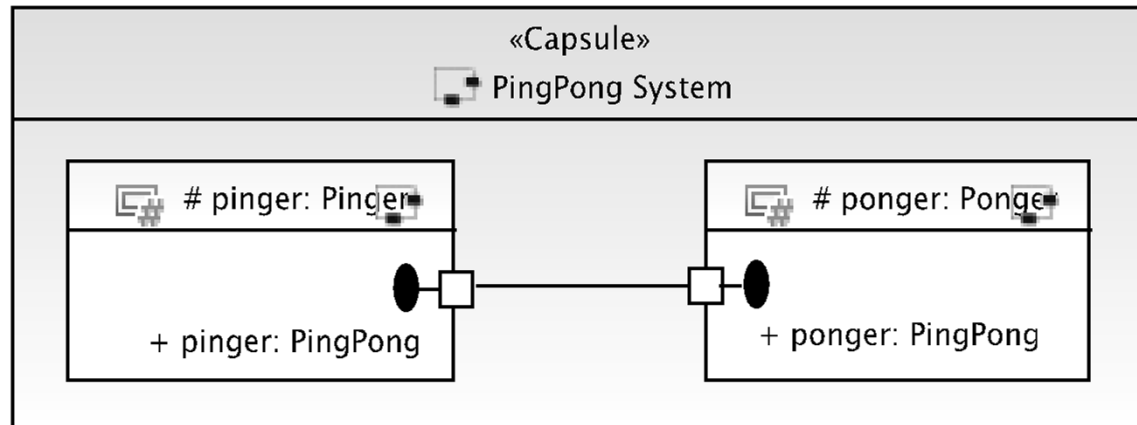
**Key idea:** Use model transformation to enrich model to allow it to support debugging operations:

- Execution stop and resume (breakpoints),
- variable access,
- collection of execution traces



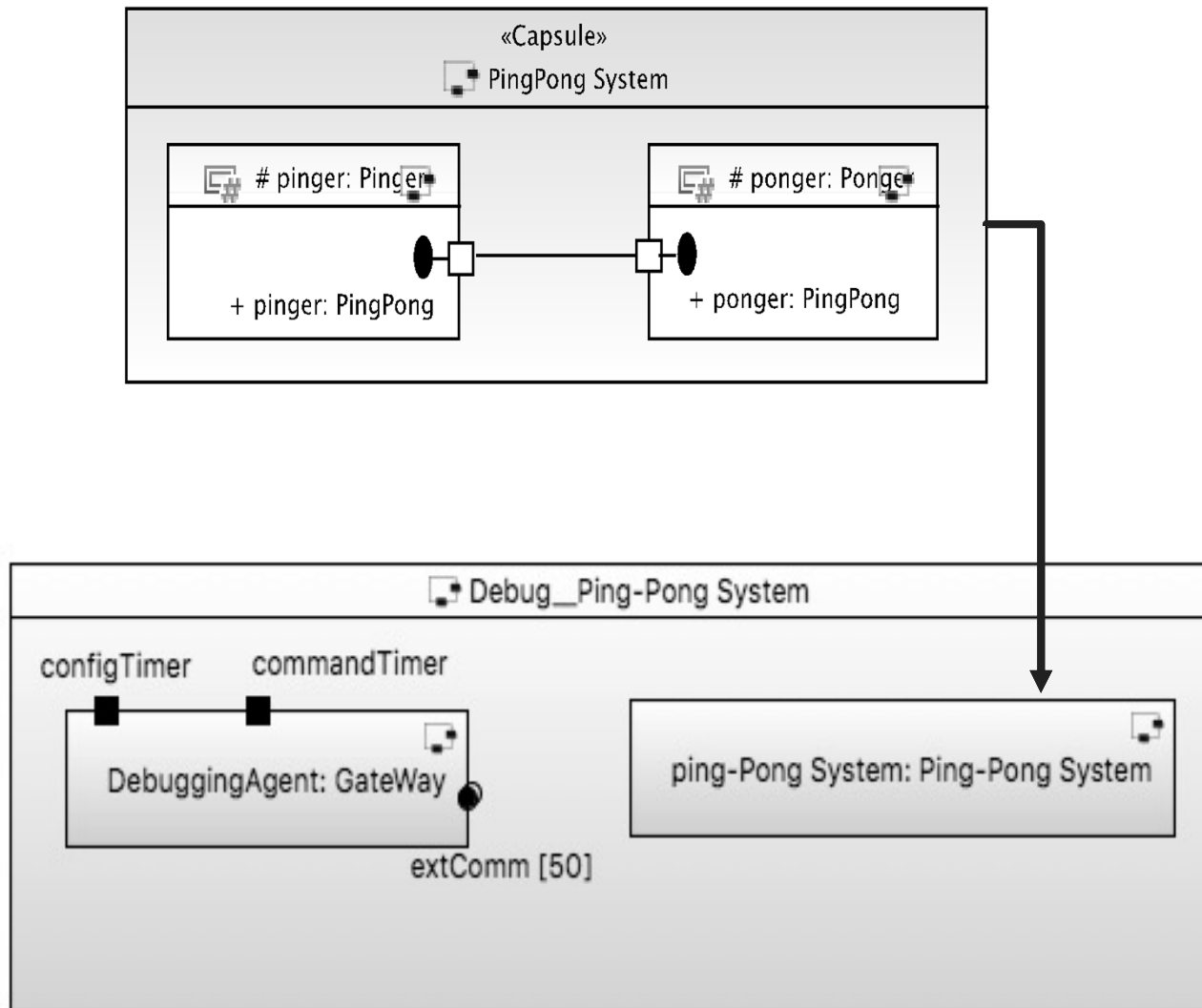


# Example: Ping Pong

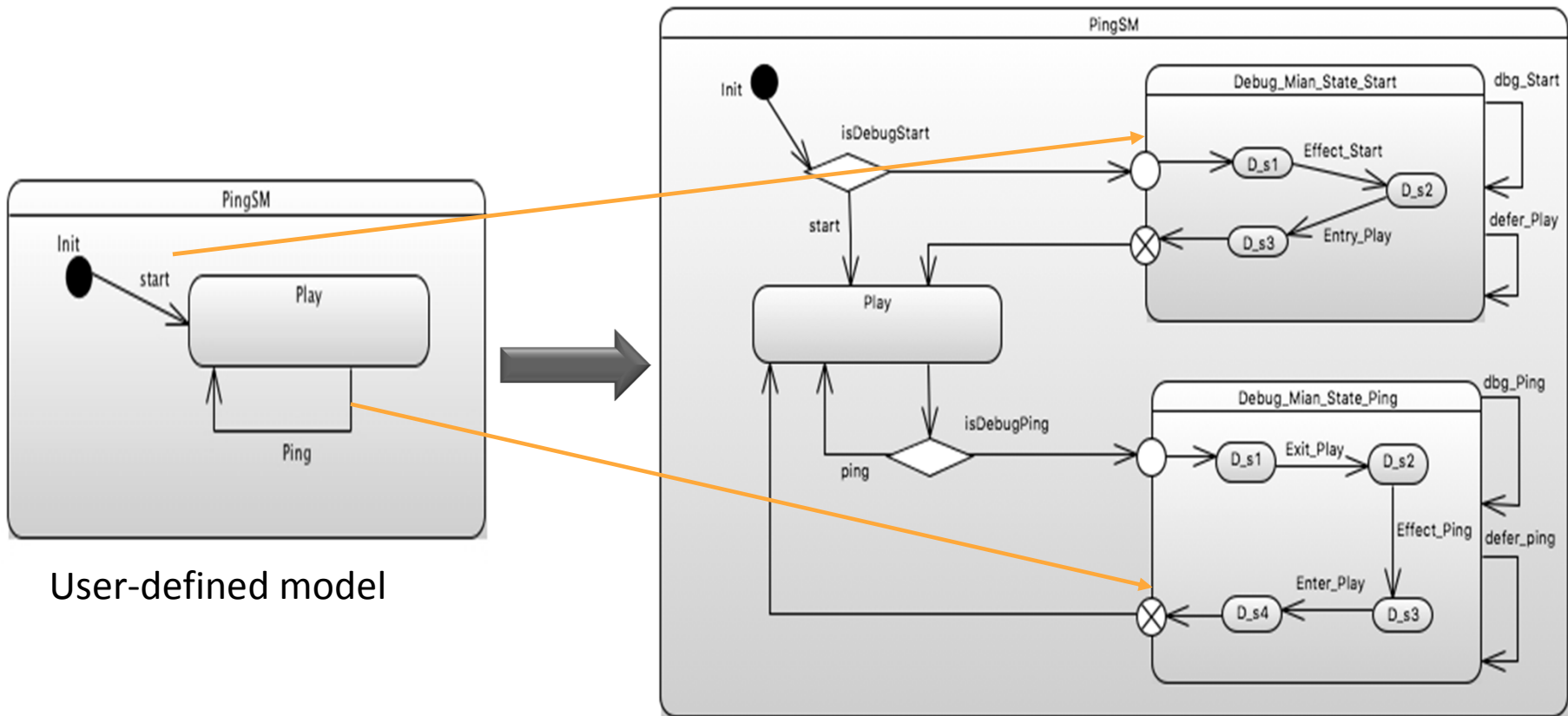


[Diagram courtesy Mojtaba Bagherzadeh]

# Transformation of Structure



# Transformation of Behaviour

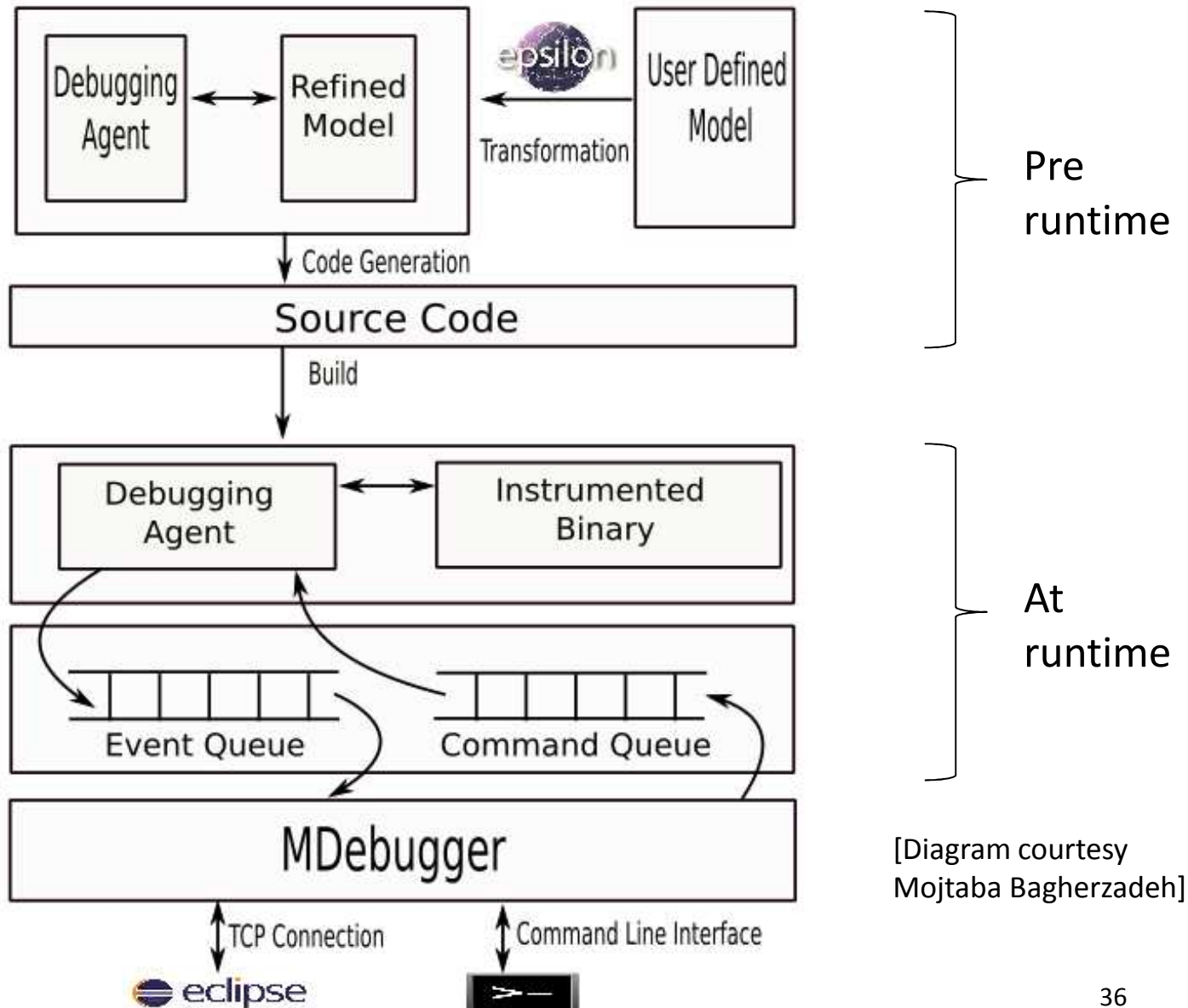


User-defined model

Instrumented model

[Diagram courtesy Mojtaba Bagherzadeh]

# Overview



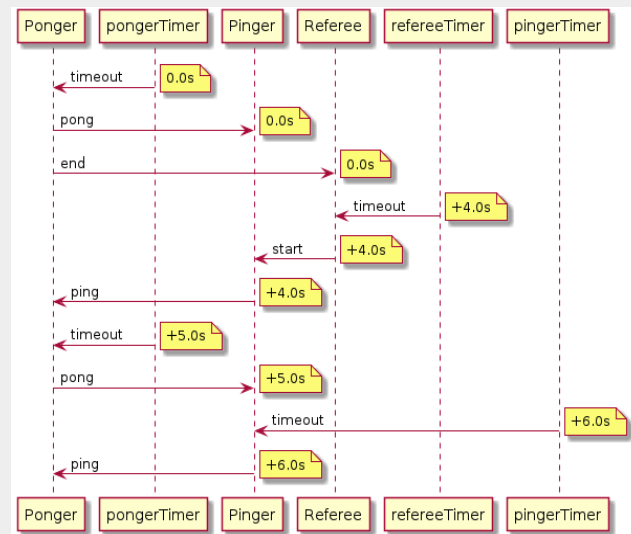
# Example: Command Line Interface

List running capsules:  
**#list**

Step execution  
**#next -c capsule1**

View last 10 events  
**#view -c capsule1 -n 10**

Generate sequence diagram:  
**#seq -c capsuleName**



# Evaluation

- **Instrumentation time**
  - ~40sec for model with 400 transitions
- **Program size**
  - comparable with existing approaches
- **Runtime performance overhead**
  - microseconds per transition

# Resources: Model-level Debugging

## ■ Paper

- M. Bagherzadeh, N. Hili, J. Dingel. Model-level, Platform-independent Debugging in the Context of the Model-driven Development of Real-time Systems. ESEC/FSE'17.



## ■ Videos

- CLI: <https://www.youtube.com/watch?v=UJ4BYSOrTOQ>
- GUI: <https://www.youtube.com/watch?v=PvPbV5QkQ9Y&t=8s>

## ■ Code with tutorial

- <https://github.com/moji1/MDebugger>

## ■ Virtual Box image

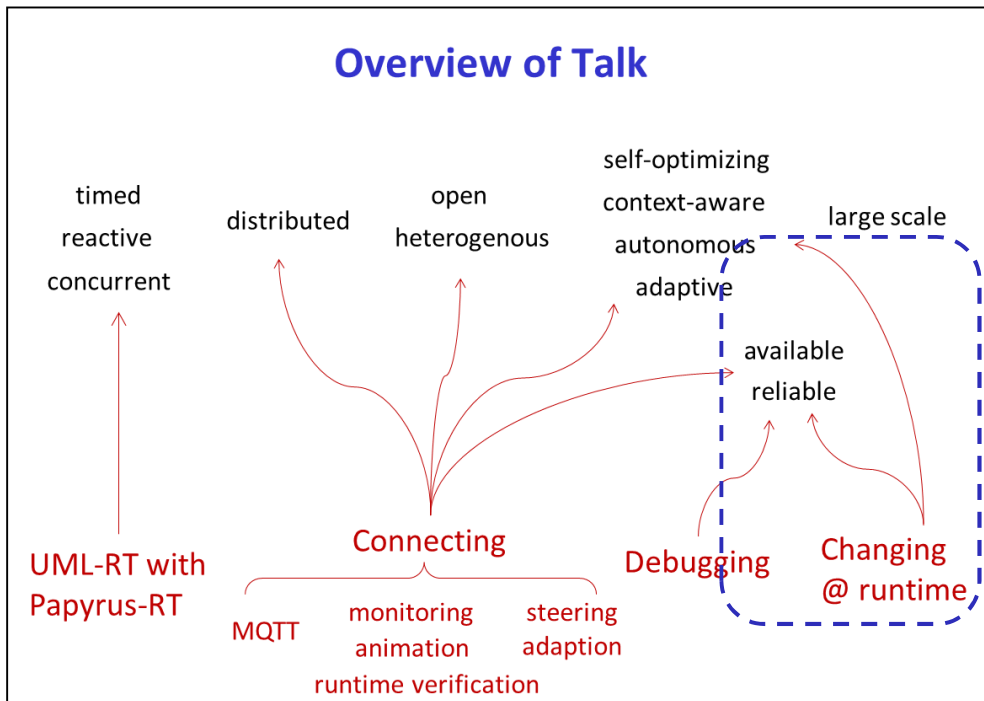
- <https://github.com/moji1/MDebugger>

# Ongoing Research 3

Changing @ runtime

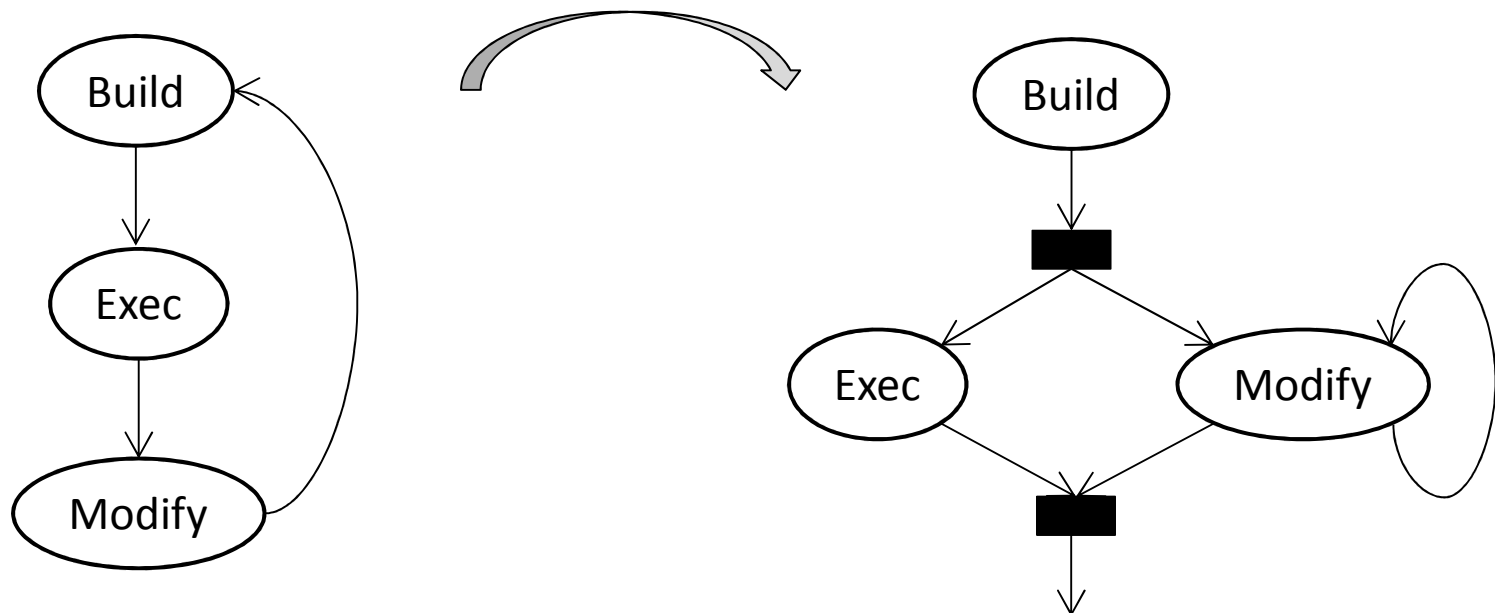


## Overview of Talk





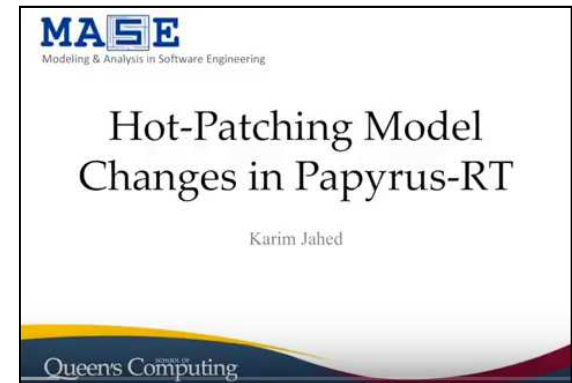
# Supporting Modifications at Runtime



- A.k.a., “hot patching/loading”, dynamic software updating
- As in, e.g., Erlang, Java Hotswap, Unreal engine, MS VS Recode

# Supporting Modifications at Runtime (Cont'd)

- Use shared, dynamically loaded and linked objects
  - Compile dynamically modifiable capsules into shared objects
  - Whenever capsule changes,
    - recompile and relink, and
    - transfer state
- Challenge
  - State transfer can lead to inconsistencies
- Demo
  - <https://youtu.be/FrJm9NTR-bc>
- Ongoing
  - Minimizing inconsistencies
  - Roll back



Ongoing Research 4

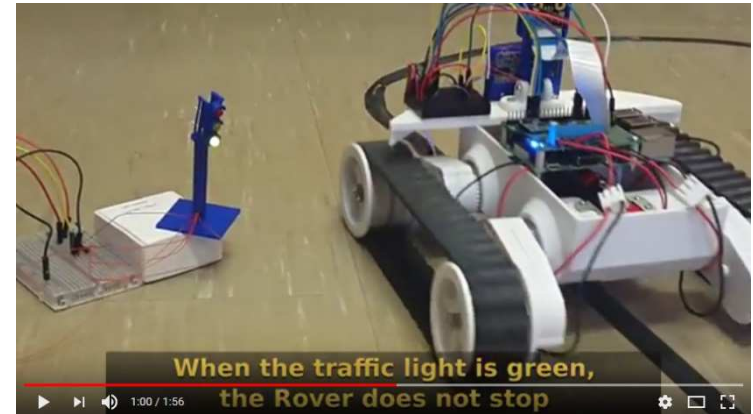


Demonstrator:  
PolarSys Rover



## ■ PolarSys Rover

- 2 motors, motor controller
- Line sensor, ultrasonic detection sensor, camera
- <https://www.polarsys.org/projects/polarsys.rover>

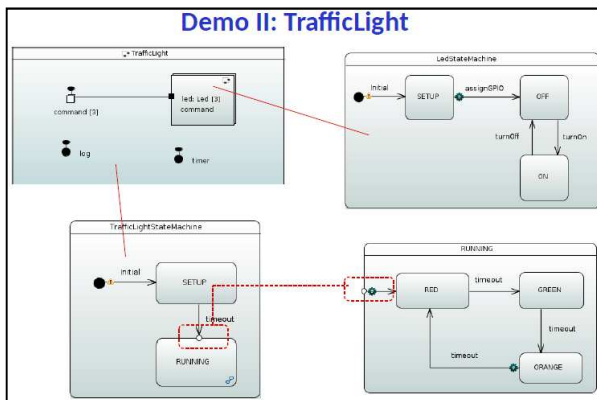


<https://www.youtube.com/watch?v=2kLhRUHGLB4>

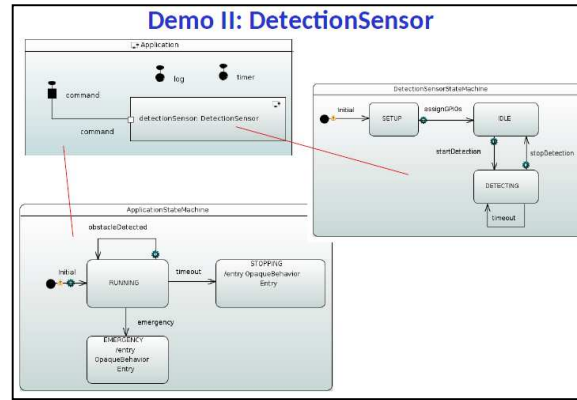
## ■ Raspberry Pi 3 Model B

- 1.2GHz 64-bit Quad-core, 1GB RAM
- WLAN, Bluetooth, 4 USB, HDMI, Ethernet

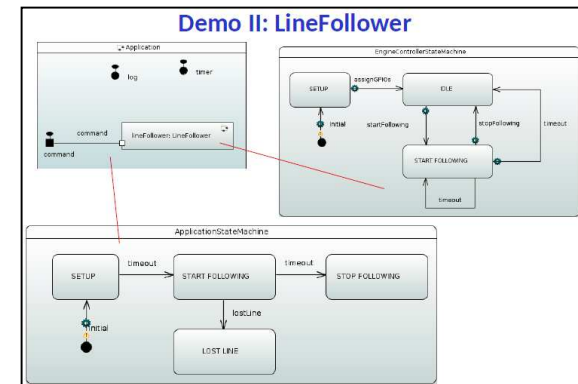
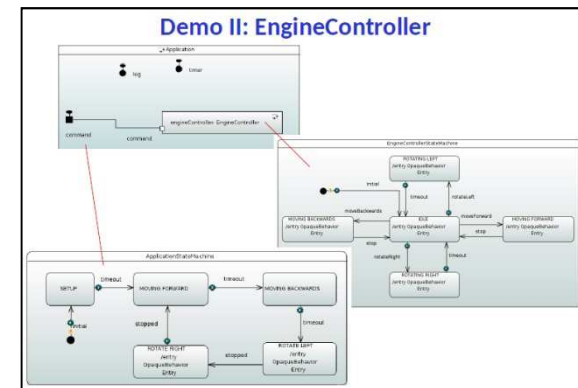
[UML-RT slides courtesy of Nicolas Hili]



J. Dingel



EXE'17





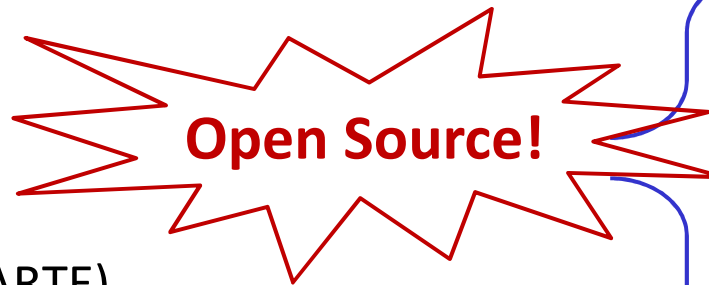
Conclusion



# Conclusion

## MDE with UML-RT and Papryrus-RT

- + Connecting (gateway, MQTT)
- + Debugging
- + Change at RT
- + Distribution
- + Deployment (MARTE)
- + Schedulability
- + Testing
- + ?



This talk

Future work

= Open source MDE tool infrastructure for (certain kinds of) IoT applications

# Resources

- <http://flux.cs.queensu.ca/mase/papyrus-rt-resources/>

# Acknowledgements

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- Harshith Vasanth Gayathri, MSc
- Sudharshan Gopikrishnan, MSc





Thank you ...

... for your attention

Hey you shrub, do you always have to have the last word?

